

Aufgabe 1

```
1 class Point:  
2  
3     n = 0  
4  
5     def __init__(self, x, y):  
6         self.x = x  
7         self.y = y  
8         Point.n += 1  
9  
10    def translate(self, x, y):  
11        self.x += x  
12        self.y += y  
13  
14    def reflection(self):  
15        self.x = -self.x  
16        self.y = -self.y  
17  
18    def __str__(self):  
19        return '{},{}'.format(self.x, self.y)  
20  
21 A = Point(2, 5)  
22 B = Point(-4, 3)  
23 A.translate(10, 20)  
24 B.reflection()  
25 print(A)  
26 print(B)  
27 print(Point.n)
```

(12,25)
(4,-3)
2

Aufgabe 2

```
1 class Example:  
2  
3     c = 3  
4  
5     def __init__(self, x):  
6         self.a = x  
7         Example.c += x  
8  
9 e1 = Example(5)  
10 e2 = Example(7)  
11 print(e1.a)  
12 print(e2.a)  
13 print(Example.c)
```

5
7
15

Aufgabe 3

```
1 class Dog():  
2  
3     species = 'Canis familiaris'  
4  
5     def __init__(self, name, age):  
6         self.name = name  
7         self.age = age  
8  
9     def speak(self, sound):  
10        print('{0} says {1}'.format(self.name, sound))  
11  
12  
13 d1 = Dog('Miles', 5)  
14 d2 = Dog('Jack', 4)  
15 print(d1.age)  
16 print(d2.name)  
17 d1.speak('Woof')  
18 d2.speak('Bow Bow')
```

5
Jack
Miles says Woof
Jack says Bow Bow

Aufgabe 4

```
1  class Kreis:  
2  
3      pi = 3.14  
4  
5      def __init__(self, radius):  
6          self.r = radius  
7  
8      def inhalt(self):  
9          return self.r**2 * Kreis.pi  
10  
11     def umfang(self):  
12         return 2 * self.r * Kreis.pi  
13  
14 k1 = Kreis(10)  
15 k2 = Kreis(1)  
16 print(k1.inhalt())  
17 print(k2.umfang())
```

314.0

6.28

Aufgabe 5

```
1  class Robot:
2
3      def __init__(self, name, x=0, y=0):
4          self.name = name
5          self.x = x
6          self.y = y
7          self.energy = 100
8
9      def go_north(self, steps):
10         self.y += steps
11         self.energy -= steps
12
13     def go_south(self, steps):
14         self.y -= steps
15         self.energy -= steps
16
17     def go_east(self, steps):
18         self.x += steps
19         self.energy -= steps
20
21     def go_west(self, steps):
22         self.x -= steps
23         self.energy -= steps
24
25     def __str__(self):
26         txt = '{0}\n'.format(self.name)
27         txt += 'Position: ({0},{1})\n'.format(self.x, self.y)
28         txt += 'Energy: {0}\n'.format(self.energy)
29         return txt
30
31 r1 = Robot('R2-D2', 3, 5)
32 r2 = Robot('Asimov')
33 r1.go_south(4)
34 r1.go_west(10)
35 r1.go_north(12)
36 r2.go_east(7)
37 r2.go_north(3)
38 r2.go_west(5)
39
40 print(r1)
41 print(r2)
```

R2-D2
Position: (-7,13)
Energy: 74

Asimov
Position: (2,3)
Energy: 85

Aufgabe 6

```
1  class Rechteck:
2      '''Klasse für Rechtecksberechnungen'''
3
4      def __init__(self, a, b):
5          self.a = a
6          self.b = b
7
8      def __str__(self):
9          return 'a={0.a}, b={0.b}'.format(self)
10
11     def inhalt(self):
12         return self.a * self.b
13
14     def umfang(self):
15         return 2*(self.a + self.b)
16
17 if __name__ == '__main__':
18
19     r1 = Rechteck(3, 2)
20     r2 = Rechteck(1, 5)
21
22     print(r1)
23     print(r1.inhalt())
24     print(r2.umfang())
```